

Fig. 1 WLI measurements of solder bump. Right: common WLI, $v=20\mu\text{m/s}$. Left: novel method with $v=500\mu\text{m/s}$ (40x undersampling). Measurements are performed with identical technology

Industrial 3D-metrology demands for **accuracy, space-bandwidth (SBP) and speed**. Many applications require an accuracy in the regime of $1\mu\text{m}$, which can easily be achieved by White-Light-Interferometers (WLI) [1]. However, WLI (and other accurate methods) are slow, specifically for **large field and high lateral resolution**. Typical measurement cycles in production lines are faster than **1 second**.

We demonstrate how to overcome this problem exploiting the physical and information theoretical margins, and by latest camera technology. We make WLI more **data-efficient**: so a much smaller **number of raw images** is sufficient. We achieve 4 Mpix images with a depth scan speed $v=0.5\text{mm/sec}$.

Physics and information theory

The Michelson interferometer is equipped with a **broadband light source**. By scanning the object along the z-axis, we obtain an interference signal (**correlogram**) in each pixel of the camera detector.

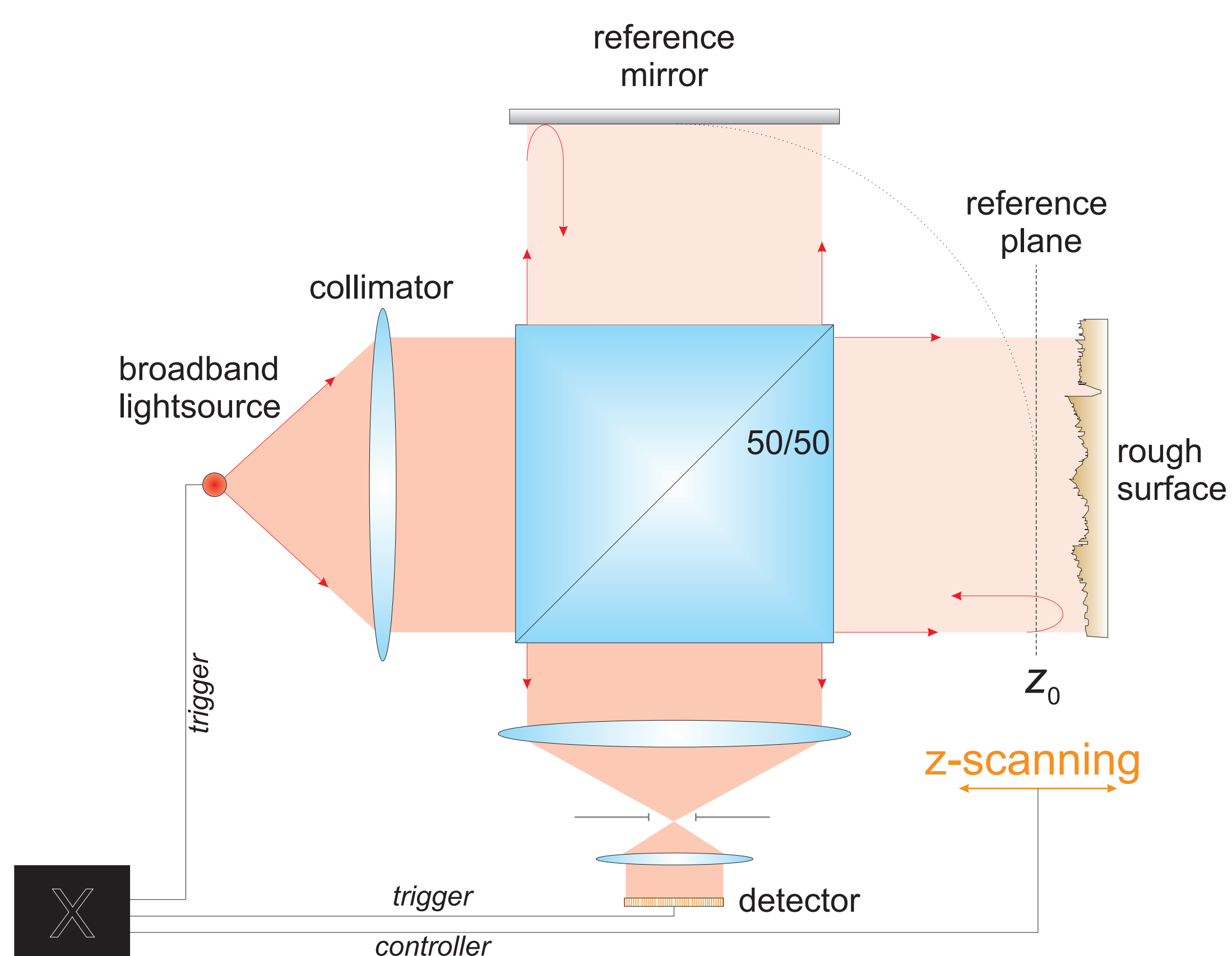


Fig. 2 Measurement principle of WLI with a rough surface.

The correlogram will be **highly undersampled** to achieve a high scanning speed v , as illustrated in Fig. 3. The high scanning speed requires synchronized strobe illumination with extremely high power.

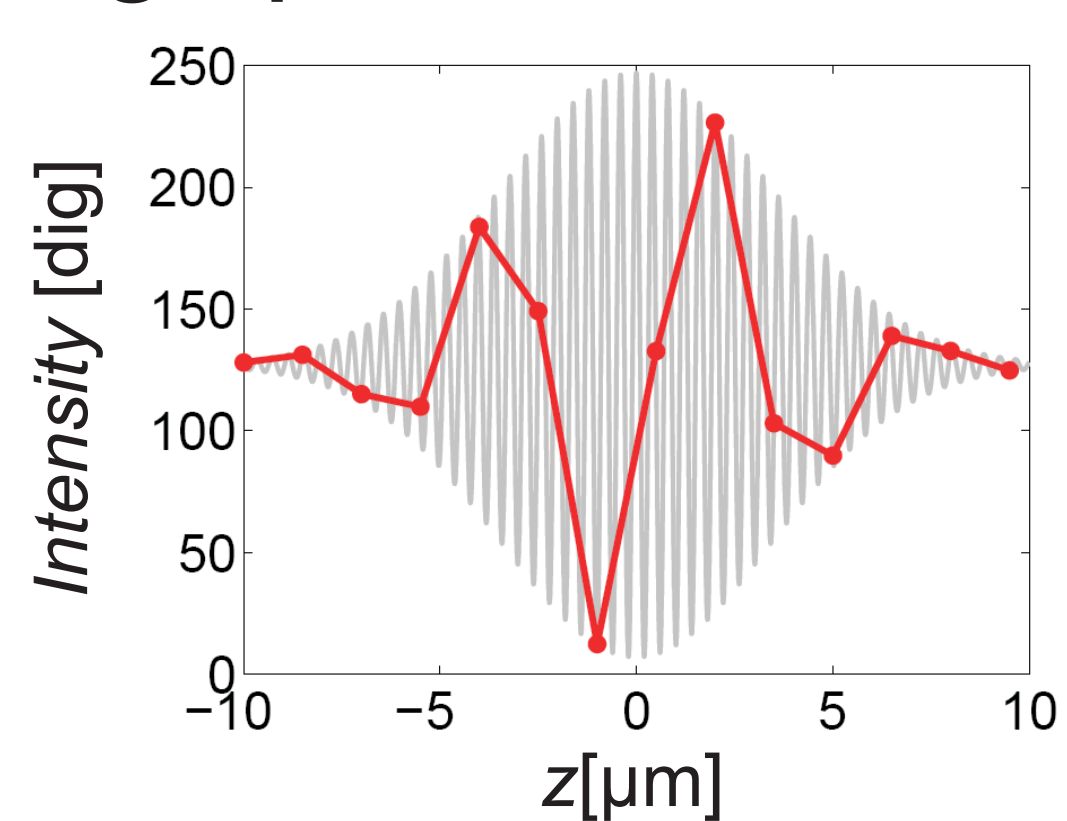


Fig. 3 Comparison of a properly sampled correlogram (grey, $0.12\mu\text{m}$ stepsize) and undersampled correlogram (red, $2\mu\text{m}$ stepsize) measured for every pixel of the detector. The position of the maximum of the envelope corresponds to the height position of the measured surface.

Technology

Meanwhile, **new 4 Megapixel cameras** are available with a continuous frame rate greater than **100 frames** per second. With **conventional sampling**, this would allow a measurement speed of “only” **$20\mu\text{m/sec}$** . We achieve a measurement speed of more than **$500\mu\text{m/sec}$** by a novel sampling scheme and novel evaluation. This is possible because we neglect the information about the phase in the correlogram and just use the **maximum** of the correlogram.

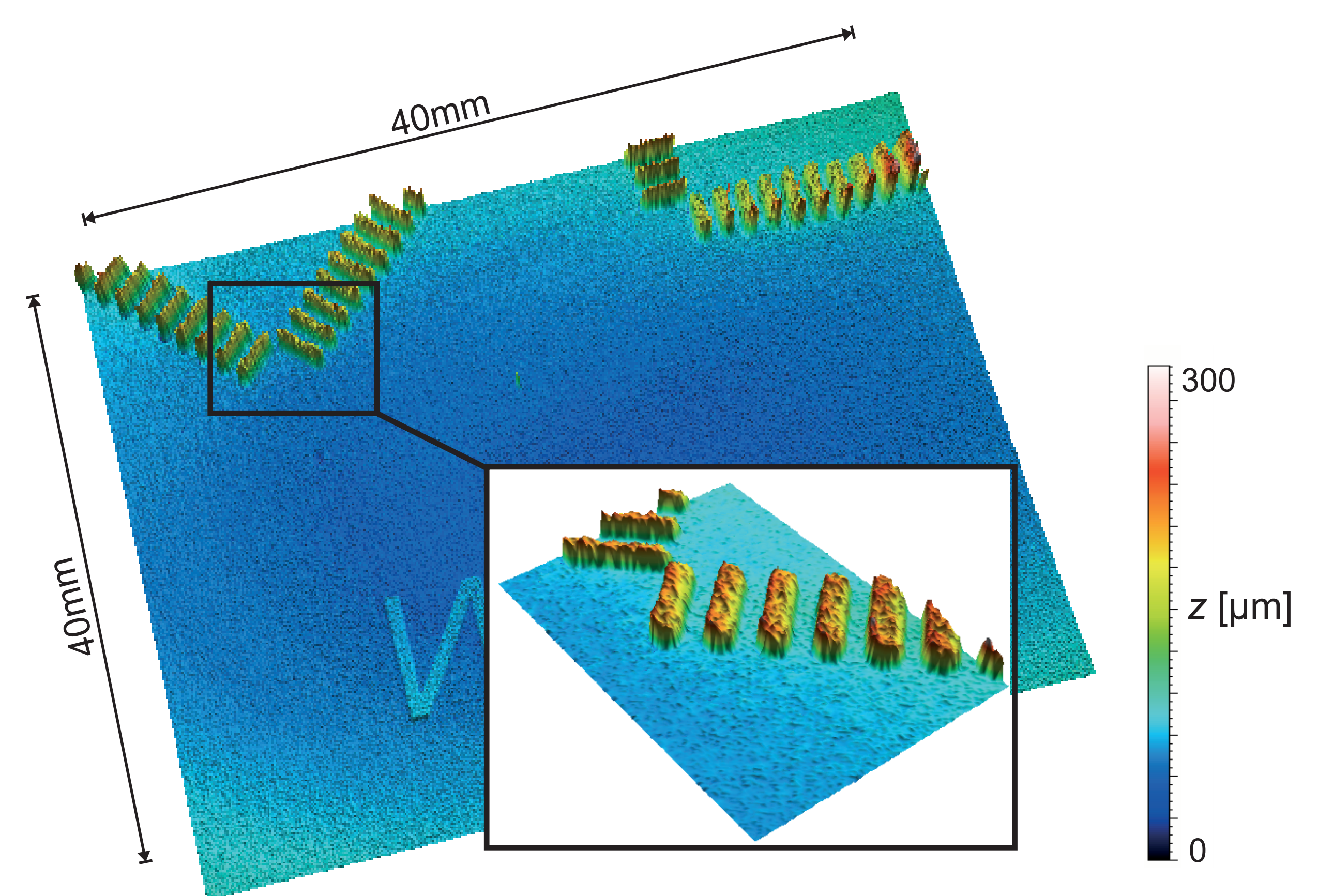


Fig. 4 Results of the measurement of an electronic board. A volume of $40\times 40\times 0.5\text{mm}$ was measured within one second.

The sensor is **available** with the following specifications [3]:

- field of view: $40\text{mm} \times 40\text{mm}$
- lateral resolution: $20\mu\text{m/pixel}$
- measurement uncertainty: $\sim 1\mu\text{m}$

[1] T. Dresel, G. Häusler, H. Venzke; „Three-dimensional sensing of rough surfaces by coherence radar”, Appl.Opt., Vol. 31, No. 7, 919-925, (1992)

[2] P. deGroot, L. Deck, “Three-Dimensional imaging by sub-Nyquist sampling of white-light interferograms”, Opt. Letters. Vol. 18, No. 17, (1993)

[3] 3D-Shape GmbH; <http://www.3d-shape.com>; [online]